12.4: Stress, Strain, and Elastic Modulus (Part 1)

Learning Objectives

- Explain the concepts of stress and strain in describing elastic deformations of materials
- Describe the types of elastic deformation of objects and materials

A model of a rigid body is an idealized example of an object that does not deform under the actions of external forces. It is very useful when analyzing mechanical systems—and many physical objects are indeed rigid to a great extent. The extent to which an object can be perceived as rigid depends on the physical properties of the material from which it is made. For example, a ping-pong ball made of plastic is brittle, and a tennis ball made of rubber is elastic when acted upon by squashing forces. However, under other circumstances, both a ping-pong ball and a tennis ball may bounce well as rigid bodies. Similarly, someone who designs prosthetic limbs may be able to approximate the mechanics of human limbs by modeling them as rigid bodies; however, the actual combination of bones and tissues is an elastic medium.

For the remainder of this section, we move from consideration of forces that affect the motion of an object to those that affect an object’s shape. A change in shape due to the application of a force is known as a deformation. Even very small forces are known to cause some deformation. Deformation is experienced by objects or physical media under the action of external forces—for example, this may be squashing, squeezing, ripping, twisting, shearing, or pulling the objects apart. In the language of physics, two terms describe the forces on objects undergoing deformation: stress and strain.

Stress is a quantity that describes the magnitude of forces that cause deformation. Stress is generally defined as force per unit area. When forces pull on an object and cause its elongation, like the stretching of an elastic band, we call such stress a tensile stress. When forces cause a compression of an object, we call it a compressive stress. When an object is being squeezed from all sides, like a submarine in the depths of an ocean, we call this kind of stress a bulk stress (or volume stress). In other situations, the acting forces may be neither tensile nor compressive, and still produce a noticeable
deformation. For example, suppose you hold a book tightly between the palms of your hands, then with one hand you press-
and-pull on the front cover away from you, while with the other hand you press-and-pull on the back cover toward you. In
such a case, when deforming forces act tangentially to the object’s surface, we call them ‘shear’ forces and the stress they
cause is called shear stress.

The SI unit of stress is the pascal (Pa). When one newton of force presses on a unit surface area of one meter squared, the
resulting stress is one pascal:

\[\text{one pascal} = 1.0\; \text{Pa} = \frac{1.0\; \text{N}}{1.0\; \text{m}^2}\]

In the British system of units, the unit of stress is ‘psi,’ which stands for ‘pound per square inch’ (lb/in
^2
). Another unit that is
often used for bulk stress is the atm (atmosphere). Conversion factors are

\[1\; \text{psi} = 6895\; \text{Pa}; \quad 1\; \text{Pa} = 1.450 \times 10^{-4}\; \text{psi}\]

An object or medium under stress becomes deformed. The quantity that describes this deformation is called strain. Strain is
given as a fractional change in either length (under tensile stress) or volume (under bulk stress) or geometry (under shear
stress). Therefore, strain is a dimensionless number. Strain under a tensile stress is called tensile strain, strain under bulk
stress is called bulk strain (or volume strain), and that caused by shear stress is called shear strain.

The greater the stress, the greater the strain; however, the relation between strain and stress does not need to be linear. Only
when stress is sufficiently low is the deformation it causes in direct proportion to the stress value. The proportionality constant
in this relation is called the elastic modulus. In the linear limit of low stress values, the general relation between stress and
strain is

\[\text{stress} = (\text{elastic modulus}) \times \text{strain}\]

As we can see from dimensional analysis of this relation, the elastic modulus has the same physical unit as stress because
strain is dimensionless.

We can also see from Equation \ref{12.33} that when an object is characterized by a large value of elastic modulus, the effect
of stress is small. On the other hand, a small elastic modulus means that stress produces large strain and noticeable
deformation. For example, a stress on a rubber band produces larger strain (deformation) than the same stress on a steel band
of the same dimensions because the elastic modulus for rubber is two orders of magnitude smaller than the elastic modulus for
steel.

The elastic modulus for tensile stress is called Young’s modulus; that for the bulk stress is called the bulk modulus; and that
for shear stress is called the shear modulus. Note that the relation between stress and strain is an observed relation, measured
in the laboratory. Elastic moduli for various materials are measured under various physical conditions, such as varying
temperature, and collected in engineering data tables for reference (Table \ref{PageIndex{1}}). These tables are valuable
references for industry and for anyone involved in engineering or construction. In the next section, we discuss strain-stress
relations beyond the linear limit represented by Equation \ref{12.33}, in the full range of stress values up to a fracture point. In the remainder of this section, we study the linear limit expressed by Equation \ref{12.33}.

<table>
<thead>
<tr>
<th>Material</th>
<th>Young’s modulus × 10^{10} Pa</th>
<th>Bulk modulus × 10^{10} Pa</th>
<th>Shear modulus × 10^{10} Pa</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aluminum</td>
<td>7.0</td>
<td>7.5</td>
<td>2.5</td>
</tr>
<tr>
<td>Bone (tension)</td>
<td>1.6</td>
<td>0.8</td>
<td>8.0</td>
</tr>
<tr>
<td>Bone (compression)</td>
<td>0.9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Brass</td>
<td>9.0</td>
<td>6.0</td>
<td>3.5</td>
</tr>
<tr>
<td>Brick</td>
<td>1.5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Concrete</td>
<td>2.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Copper</td>
<td>11.0</td>
<td>14.0</td>
<td>4.4</td>
</tr>
<tr>
<td>Crown glass</td>
<td>6.0</td>
<td>5.0</td>
<td>2.5</td>
</tr>
<tr>
<td>Granite</td>
<td>4.5</td>
<td>4.5</td>
<td>2.0</td>
</tr>
<tr>
<td>Hair (human)</td>
<td>1.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hardwood</td>
<td>1.5</td>
<td></td>
<td>1.0</td>
</tr>
<tr>
<td>Iron</td>
<td>21.0</td>
<td>16.0</td>
<td>7.7</td>
</tr>
<tr>
<td>Lead</td>
<td>1.6</td>
<td>4.1</td>
<td>0.6</td>
</tr>
<tr>
<td>Marble</td>
<td>6.0</td>
<td>7.0</td>
<td>2.0</td>
</tr>
<tr>
<td>Nickel</td>
<td>21.0</td>
<td>17.0</td>
<td>7.8</td>
</tr>
<tr>
<td>Polystyrene</td>
<td>3.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Silk</td>
<td>6.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Spider thread</td>
<td>3.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Steel</td>
<td>20.0</td>
<td>16.0</td>
<td>7.5</td>
</tr>
<tr>
<td>Acetone</td>
<td></td>
<td></td>
<td>0.07</td>
</tr>
<tr>
<td>Ethanol</td>
<td></td>
<td></td>
<td>0.09</td>
</tr>
<tr>
<td>Glycerin</td>
<td></td>
<td></td>
<td>0.45</td>
</tr>
<tr>
<td>Material</td>
<td>Young’s modulus × 10^{10} Pa</td>
<td>Bulk modulus × 10^{10} Pa</td>
<td>Shear modulus × 10^{10} Pa</td>
</tr>
<tr>
<td>----------</td>
<td>-----------------------------</td>
<td>-----------------------------</td>
<td>-----------------------------</td>
</tr>
<tr>
<td>Mercury</td>
<td>2.5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Water</td>
<td>0.22</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Tensile or Compressive Stress, Strain, and Young’s Modulus**

Tension or compression occurs when two antiparallel forces of equal magnitude act on an object along only one of its dimensions, in such a way that the object does not move. One way to envision such a situation is illustrated in Figure (PageIndex{1}). A rod segment is either stretched or squeezed by a pair of forces acting along its length and perpendicular to its cross-section. The net effect of such forces is that the rod changes its length from the original length \(L_0\) that it had before the forces appeared, to a new length \(L\) that it has under the action of the forces. This change in length \(\Delta L = L - L_0\) may be either elongation (when \(L\) is larger than the original length \(L_0\)) or contraction (when \(L\) is smaller than the original length \(L_0\)). Tensile stress and strain occur when the forces are stretching an object, causing its elongation, and the length change \(\Delta L\) is positive. Compressive stress and strain occur when the forces are contracting an object, causing its shortening, and the length change \(\Delta L\) is negative.

In either of these situations, we define stress as the ratio of the deforming force \(F_{\perp}\) to the cross-sectional area \(A\) of the object being deformed. The symbol \(F_{\perp}\) that we reserve for the deforming force means that this force acts perpendicularly to the cross-section of the object. Forces that act parallel to the cross-section do not change the length of an object. The definition of the tensile stress is

\[
\text{tensile stress} = \frac{F_{\perp}}{A} \label{12.34}
\]

Tensile strain is the measure of the deformation of an object under tensile stress and is defined as the fractional change of the object’s length when the object experiences tensile stress

\[
\text{tensile strain} = \frac{\Delta L}{L_0} \label{12.35}
\]

Compressive stress and strain are defined by the same formulas, Equations \ref{12.34} and \ref{12.35}, respectively. The only difference from the tensile situation is that for compressive stress and strain, we take absolute values of the right-hand sides in Equation \ref{12.34} and \ref{12.35}.

UC Davis ChemWiki is licensed under a Creative Commons Attribution-Noncommercial-Share Alike 3.0 United States License.
When an object is in either tension or compression, the net force on it is zero, but the object deforms by changing its original length $L_0$. (a) Tension: The rod is elongated by $\Delta L$. (b) Compression: The rod is contracted by $\Delta L$. In both cases, the deforming force acts along the length of the rod and perpendicular to its cross-section. In the linear range of low stress, the cross-sectional area of the rod does not change.

Young’s modulus $Y$ is the elastic modulus when deformation is caused by either tensile or compressive stress, and is defined by Equation \ref{12.33}. Dividing this equation by tensile strain, we obtain the expression for Young’s modulus:

\[
Y = \frac{\text{tensile stress}}{\text{tensile strain}} = \frac{\frac{F_{\perp}}{A}}{\frac{\Delta L}{L_0}} = \frac{F_{\perp}}{A} = \frac{L_0}{\Delta L} \tag{12.36}
\]

Example \ref{PageIndex{1}}: Compressive Stress in a Pillar

A sculpture weighing 10,000 N rests on a horizontal surface at the top of a 6.0-m-tall vertical pillar Figure \ref{PageIndex{1}}. The pillar’s cross-sectional area is 0.20 m\(^2\) and it is made of granite with a mass density of 2700 kg/m\(^3\). Find the compressive stress at the cross-section located 3.0 m below the top of the pillar and the value of the compressive strain of the top 3.0-m segment of the pillar.
Strategy

First we find the weight of the 3.0-m-long top section of the pillar. The normal force that acts on the cross-section located 3.0 m down from the top is the sum of the pillar’s weight and the sculpture’s weight. Once we have the normal force, we use Equation 12.34 to find the stress. To find the compressive strain, we find the value of Young’s modulus for granite in Table \(\PageIndex{1}\) and invert Equation \ref{12.36}.

Solution

The volume of the pillar segment with height \(h = 3.0\ \text{m}\) and cross-sectional area \(A = 0.20\ \text{m}^2\) is

\[
V = Ah = (0.20\ \text{m}^2)(3.0\ \text{m}) = 0.60\ \text{m}^3.
\]

With the density of granite \(\rho = 2.7 \times 10^3\ \text{kg/m}^3\), the mass of the pillar segment is

\[
m = \rho V = (2.7 \times 10^3\ \text{kg/m}^3)(0.60\ \text{m}^3) = 1.62 \times 10^3\ \text{kg}.
\]

The weight of the pillar segment is

\[
w_p = mg = (1.62 \times 10^3\ \text{kg})(9.80\ \text{m/s}^2) = 1.562 \times 10^4\ \text{N}.
\]

The weight of the sculpture is \(w_s = 1.0 \times 10^4\ \text{N}\), so the normal force on the cross-sectional surface located 3.0 m below the sculpture is

\[
F_{\perp} = w_p + w_s = (1.562 + 1.0) \times 10^4\ \text{N} = 2.562 \times 10^4\ \text{N}.
\]
Therefore, the stress is
\[
\text{stress} = \frac{F_{\perp}}{A} = \frac{2.568 \times 10^4 \text{ N}}{0.20 \text{ m}^2} = 1.284 \times 10^5 \text{ Pa} = 128.4 \text{ kPa}
\]

Young’s modulus for granite is \( Y = 4.5 \times 10^7 \text{ Pa} \). Therefore, the compressive strain at this position is
\[
\text{strain} = \frac{\text{stress}}{Y} = \frac{128.4 \text{ kPa}}{4.5 \times 10^7 \text{ kPa}} = 2.85 \times 10^{-6}
\]

**Significance**

Notice that the normal force acting on the cross-sectional area of the pillar is not constant along its length, but varies from its smallest value at the top to its largest value at the bottom of the pillar. Thus, if the pillar has a uniform cross-sectional area along its length, the stress is largest at its base.

Exercise \( \PageIndex{2} \)

Find the compressive stress and strain at the base of Nelson’s column.

Example \( \PageIndex{2} \): Stretching a Rod

A 2.0-m-long steel rod has a cross-sectional area of 0.30 cm\(^2\). The rod is a part of a vertical support that holds a heavy 550-kg platform that hangs attached to the rod’s lower end. Ignoring the weight of the rod, what is the tensile stress in the rod and the elongation of the rod under the stress?

**Strategy**

First we compute the tensile stress in the rod under the weight of the platform in accordance with Equation 12.34. Then we invert Equation 12.36 to find the rod’s elongation, using \( L_0 = 2.0 \text{ m} \). From Table 12.1, Young’s modulus for steel is \( Y = 2.0 \times 10^{11} \text{ Pa} \).

**Solution**

Substituting numerical values into the equations gives us
\[
\begin{split}
\frac{F_{\perp}}{A} & = \frac{(550 \text{ kg})(9.8 \text{ m/s}^2)}{3.0 \times 10^{-5} \text{ m}^2} = 1.8 \times 10^8 \text{ Pa} \\
\Delta L & = \frac{F_{\perp}}{A} \frac{L_0}{Y} = (1.8 \times 10^8 \text{ Pa}) \left(\dfrac{2.0 \text{ m}}{2.0 \times 10^{11} \text{ Pa}}\right) = 1.8 \times 10^{-3} \text{ m} = 1.8 \text{ mm}
\end{split}
\]

**Significance**

Similarly as in the example with the column, the tensile stress in this example is not uniform along the length of the rod. Unlike in the previous example, however, if the weight of the rod is taken into consideration, the stress in the rod is largest at the top and smallest at the bottom of the rod where the equipment is attached.
Exercise 

A 2.0-m-long wire stretches 1.0 mm when subjected to a load. What is the tensile strain in the wire?

Objects can often experience both compressive stress and tensile stress simultaneously Figure (b). One example is a long shelf loaded with heavy books that sags between the end supports under the weight of the books. The top surface of the shelf is in compressive stress and the bottom surface of the shelf is in tensile stress. Similarly, long and heavy beams sag under their own weight. In modern building construction, such bending strains can be almost eliminated with the use of I-beams Figure (c).

Figure (a): An object bending downward experiences tensile stress (stretching) in the upper section and compressive stress (compressing) in the lower section. (b) Elite weightlifters often bend iron bars temporarily during lifting, as in the 2012 Olympics competition. (credit b: modification of work by Oleksandr Kocherzhenko)

Figure (c): Steel I-beams are used in construction to reduce bending strains. (credit: modification of work by "US Army Corps of Engineers Europe District"/Flickr)

Simulation

A heavy box rests on a table supported by three columns. View this demonstration to move the box to see how the compression (or tension) in the columns is affected when the box changes its position.

Contributors and Attributions

- Samuel J. Ling (Truman State University), Jeff Sanny (Loyola Marymount University), and Bill Moebs with many contributing authors. This work is licensed by OpenStax University Physics under a Creative Commons Attribution License (by 4.0).